

## **Basic measures of strain**

Note: the following formulas are based on Ramsay, J.G., and Huber, M.I. (1983) *The Techniques of Modern Structural Geology, Volume 1: Strain Analysis*, Academic Press, London, but with sign convention modified for clockwise measurement of angles and shear strains

### **Strain in one dimension**

**Extension** (sometimes elongation)  $e = (l-l_0)/l_0$

**Stretch**  $S = l/l_0 = 1+e$

**Quadratic elongation**  $\lambda = l^2/l_0^2 = (1+e)^2$

**Natural strain**  $\varepsilon = \ln(S) = \ln(1+e) = \ln(l/l_0)$

where original length is  $l_0$  and new length is  $l$

**Engineering shear strain**  $\gamma = \tan \psi$

**Tensor shear strain**  $e_s = 0.5 \tan \psi$

where angle of shear is  $\psi$

### **Strain in 2 dimensions**

Principal strains are designated by subscripts 1 and 3, e.g. principal elongations are  $e_1 > e_3$   
principal stretches are  $S_1=X$ ,  $S_3=Z$

**Strain ratio**  $R_s = S_1/S_3$

**Dilation**  $1+\Delta = S_1 S_3$

### **Fundamental strain equations (Mohr circle)**

For a line at an angle  $\phi'$  from the  $S_1$  axis,

if  $\lambda' = l'/\lambda$  and  $\gamma' = \gamma/\lambda$  then

$$\lambda' = \frac{\lambda'_3 + \lambda'_1}{2} - \frac{\lambda'_3 - \lambda'_1}{2} \cos(2\theta)$$

and

$$\gamma' = \frac{\lambda'_3 - \lambda'_1}{2} \sin(2\theta)$$

If  $\lambda'$  is plotted against  $\gamma'$  these are the equations of a

circle centred at  $\lambda = \frac{\lambda'_3 + \lambda'_1}{2}$  with radius  $\frac{\lambda'_3 - \lambda'_1}{2}$

### **Shear zones**

For a simple shear zone with angle of shear  $\psi$ , shear strain  $\gamma$ , the extension axis  $S_1$  is inclined to the shear zone boundary with angle  $\theta$  given by:

$$\gamma = \tan(\psi) = 2 / \tan(2\theta)$$

### **Reorientation of lines from strain ellipse**

For a line with initial orientation  $\alpha$  and orientation after deformation  $\alpha'$

$$\tan(\alpha - \theta) / \tan(\alpha' - \theta) = R_s$$

where  $R_s$  is the strain ratio,  $\theta$  is initial clockwise angle of  $S_1$  from x axis;  $\theta'$  is clockwise angle of  $S_1$  from x axis after deformation.

### **Strain in 3 dimensions**

Principal strains are designated by subscripts 1, 2 and 3, e.g. principal elongations are  $e_1 > e_2 > e_3$

Principal stretches are  $S_1=X$ ,  $S_2=Y$ ,  $S_3=Z$

**Dilation**  $1+\Delta = S_1 S_2 S_3$

**Condition for plane strain:**  $S_2=1$ ;  $S_1 S_3=1$

## **Basic measures of stress**

### **Stress Tensor**

$$T = \begin{pmatrix} \sigma_{xx} & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & \sigma_{yy} & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & \sigma_{zz} \end{pmatrix}$$

where  $\sigma_{xx}$  is normal stress on plane x

and  $\sigma_{xy}$  is shear stress on plane x parallel to axis y

### **Mean stress**

If the principal stresses are  $\sigma_1$   $\sigma_2$   $\sigma_3$  then:

$$\sigma_m = (\sigma_1 + \sigma_2 + \sigma_3)/3$$

### **Differential stress**

$$\sigma_d = \sigma_1 - \sigma_3$$

### **Deviatoric stress**

$$T_d = \begin{pmatrix} \sigma_{xx} - \sigma_m & \sigma_{xy} & \sigma_{xz} \\ \sigma_{yx} & \sigma_{yy} - \sigma_m & \sigma_{yz} \\ \sigma_{zx} & \sigma_{zy} & \sigma_{zz} - \sigma_m \end{pmatrix}$$

### **Stress on a plane**

For a plane with unit normal vector vector  $\mathbf{x}$ ,

$$\boldsymbol{\sigma} = T \cdot \mathbf{x}$$

Resolved normal stress  $\sigma_n = \boldsymbol{\sigma} \cdot \mathbf{x}$

If  $\sigma$  is the magnitude of the stress on the plane,  $\sigma_n$  is the normal stress and  $\sigma_s$  is the shear stress, then:

$$\sigma^2 = \sigma_n^2 + \sigma_s^2$$