

Vector operations

Coordinate systems

For local structural observations, we use a geographic coordinate system. Axis x points east, axis y points north, and axis z points up. Note that other coordinate systems are possible.

For calculations dealing with the whole Earth we use a coordinate system in which the origin is at the centre of the Earth. Axis x = points towards the intersection of the equator and the Greenwich meridian, y is towards the intersection of the equator and 90°E, and z = is towards the north pole.

Representation of vectors

In the following, vector **a** is represented $\begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix}$

with components in directions east, north and up.

In printed text, vectors are bold. In handwritten text, vectors are underlined thus a

Magnitude of vector **a** is represented by

$$a \text{ or } |\mathbf{a}| = \sqrt{a_x^2 + a_y^2 + a_z^2}$$

Unit vector in same direction as **a**

$$\hat{\mathbf{a}} = \begin{pmatrix} a_x/|\mathbf{a}| \\ a_y/|\mathbf{a}| \\ a_z/|\mathbf{a}| \end{pmatrix}$$

Basic vector operations

Vector addition

$$\begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} + \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = \begin{pmatrix} a_x + b_x \\ a_y + b_y \\ a_z + b_z \end{pmatrix}$$

Vector dot product $\mathbf{a} \cdot \mathbf{b} = ab \cos \theta$ where θ is the angle between **a** and **b**

$$\begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \cdot \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = a_x b_x + a_y b_y + a_z b_z$$

Vector cross product

$$\begin{pmatrix} a_x \\ a_y \\ a_z \end{pmatrix} \times \begin{pmatrix} b_x \\ b_y \\ b_z \end{pmatrix} = \begin{pmatrix} a_y b_z - b_y a_z \\ a_z b_x - b_z a_x \\ a_x b_y - b_x a_y \end{pmatrix}$$

Vectors and Orientation data

Planes and poles

Plunge (P) and trend (T) of pole from strike (S) and dip (D) of plane

$$P = 90 - D \quad T = S - 90^\circ \text{ or } S + 270^\circ$$

Strike (S) and dip (D) of plane from plunge (P) and trend (T) of pole

$$D = 90 - P \quad S = T + 90^\circ \text{ or } T - 270^\circ$$

Direction cosines

Vector components of a unit vector (direction cosines) (l,m,n) from plunge (P) and trend (T)

$$l = \sin T \cos P$$

$$m = \cos T \cos P$$

$$n = -\sin P$$

Plunge (P) and trend (T) from direction cosines (l,m,n) (components of unit vector)

$$T = \tan^{-1}(l/m) \text{ if } m \text{ is positive or}$$

$$T = \tan^{-1}(l/m) + 180 \text{ if } m \text{ is negative}$$

$$P = -\sin^{-1} n$$

Plunge (P) and trend (T) from components of a general vector (x,y,z)

$$T = \tan^{-1}(x/y) \text{ if } m \text{ is positive or}$$

$$T = \tan^{-1}(x/y) + 180 \text{ if } m \text{ is negative}$$

$$P = -\sin^{-1}(z/\sqrt{x^2 + y^2 + z^2})$$

Vector components of a pole to a plane (direction cosines) (l,m,n) from strike (S) and dip (D)

$$l = -\cos S \sin D$$

$$m = \sin S \sin D$$

$$n = -\cos D$$

Strike (S) and dip (D) from direction cosines of a pole (l,m,n)

$$T = \tan^{-1}(l/m) + 90 \text{ if } m \text{ is positive or}$$

$$T = \tan^{-1}(l/m) + 270 \text{ if } m \text{ is negative}$$

$$P = -\cos^{-1} n$$

Statistics of orientation data

Statistics for a set of unit vectors: $\hat{\mathbf{a}}_1, \hat{\mathbf{a}}_2, \hat{\mathbf{a}}_3 \dots \hat{\mathbf{a}}_n$

$$\text{Vector sum } \mathbf{R} = (\hat{\mathbf{a}}_1 + \hat{\mathbf{a}}_2 + \hat{\mathbf{a}}_3 + \dots + \hat{\mathbf{a}}_n)$$

$$\text{Resultant } R = |\mathbf{R}|$$

$$\text{Vector mean } \mathbf{r} = \overline{\mathbf{R}} = \mathbf{R}/n$$

$$\text{Mean resultant } r = |\mathbf{r}| = R/n$$

Direction cosine matrix of a set of unit vectors

$$\text{The matrix } \begin{pmatrix} \sum l^2 & \sum lm & \sum ln \\ \sum lm & \sum m^2 & \sum mn \\ \sum ln & \sum mn & \sum n^2 \end{pmatrix}$$

has eigenvectors $\mathbf{E}_1, \mathbf{E}_2, \mathbf{E}_3$, and eigenvalues $E_1 \leq E_2 \leq E_3$